

# MDrive<sup>®</sup> Hybrid

Integrated motion systems with  
Hybrid Motion Technology<sup>™</sup>



**MDrive 23 Hybrid**  
Motion Control



MDrive® Hybrid Motion Control, fully programmable  
 Sizes: 17, 23 & 34ac

### Presentation

The MDrive® Hybrid Motion Control is a very compact motion system that solves many servo applications with a low cost solution. The system includes a 1.8° 2-phase stepper motor integrated with a fully programmable controller, high performance microstepping drive, internal encoder integral to system operation, and Hybrid Motion Technology™ (HMT). HMT combines the best of servo and stepper motor technologies, while delivering unique capabilities and enhancements over both. These stand-alone motion control solutions can be used without any external controller.

With MDrive Hybrid integrated motion control systems, point-to-point positioning, torque mode and velocity control are all user programmed with pre-installed MCode software, a simple language that uses 1 to 2 character instructions, and an easy-to-use terminal emulator program that is provided. Communication is via RS-422/485 or Ethernet. (1)

MDrive Hybrid systems with Ethernet are programmed with the same MCode instruction set used for the RS-422/485 products. Ethernet products also support MODBUS/TCP application protocol, per specification Version 1.1b, with operation in immediate mode, not as programmable products.

A USB to RS-422/485 Communications Converter is available for ease of connecting to a user's PC. Connectivity options range from all-inclusive QuickStart Kits to individual interfacing cables and mating connector kits to build your own cables.

### Application areas

The MDrive Hybrid is ideal for machine builders who want a low cost alternative to servo motors and brushed DC motors. The highly compact, integrated electronics of the MDrive Hybrid reduce the potential for problems due to electrical noise by eliminating the cable between motor and drive. This stepper-based system requires no tuning, and provides real-time closed loop control through an internal encoder.

These compact, powerful and cost effective motion control solutions deliver unsurpassed smoothness and performance that will reduce system cost, design and assembly time for a large range of motor applications — both servo and stepper.

### Features

- Highly integrated microstepping drive and high torque 1.8° 2-phase stepper motor
- Fully programmable motion controller
- HMT control for exceptional performance
- Internal encoder
- Single supply: from +12 up to +75 VDC or 120 and 240 VAC
- Cost effective
- Extremely compact
- 20 microstep resolutions up to 51,200 steps per rev including: Degrees, Metric, Arc Minutes
- Several motor stack lengths available
- Available options:
  - Long life linear actuator (2)
  - Rear control knob for manual position
  - QuickStart Kit
  - Drive Protection Module
- Graphical user interface provided for quick and easy configuration and programming

(1) Ethernet only available with MDrive23Hybrid systems.

(2) Only available with MDrive23Hybrid systems. See separate documentation.



Motion Control specifications						
Input power	Voltage	VDC	MDrive 17	MDrive 23	MDrive 34ac	
		VAC	12 to 48	12 to 60	—	—
	Current maximum (1)		2.0A	3.5A	120	240
Thermal	Operating temp non-condensing	Heat sink	-40° to +85°C	-40° to +85°C	95 to 132 VAC @ 50/60 Hz	
		Motor	-40° to +100°C	-40° to +100°C	95 to 264 VAC @ 50/60 Hz	
	Open-drain type		not applicable	not applicable	-40° to +75°C	
Protection	Type		over temperature, short circuit, transient over voltage, over voltage, inductive clamp			
Auxiliary logic input	Voltage range (2)		+12 to +24 VDC			
Analog input	Resolution		10 bit			
General purpose I/O	Voltage range		0 to +5 VDC, 0 to +10 VDC, 0-20 mA, 4-20 mA			
	Number		8			
	Type		sourcing or sinking outputs/inputs			
	Logic range		Sourcing outputs +12 to +24 VDC			
	Output sink/source current		Inputs and sinking outputs tolerant to +24 VDC, inputs TTL level compatible			
Communication	Protection		Up to 600 mA per channel			
	Type		Over temp, short circuit, transient, over voltage, inductive clamp			
	Baud rate		RS-422/485 or Ethernet (3)			
Motion	Closed loop configuration with encoder	Encoder type	4.8 to 115.2 kbps (4)			
		Steps per revolution	Internal, magnetic			
		Encoder resolution	51200			
	Counters	Type	1000 lines/4000 edges per rev			
		Edge rate maximum	position, encoder/32 bit			
	Velocity	Range	5 MHz			
		Resolution	+/- 5,000,000 steps per second			
	Accel/Decel	Range	0.5961 steps per second			
		Resolution	1.5 x 10 <sup>9</sup> steps per second <sup>2</sup>			
	High speed I/O	Position capture	Input filter range	90.9 steps per second <sup>2</sup>		
			Resolution	50 nS to 12.9 µS (10 MHz to 38.8 kHz)		
Trip Output		Speed/resolution/threshold	32 bit			
Software	Program storage	Type/size	flash/6384 bytes			
	User registers	Four 32 bit				
	User program labels & variables	192				
	Math functions	+, -, x, +, >, <, =, <=, >=, AND, OR, XOR, NOT				
	Branch functions	Branch and Call				
	General purpose I/O functions	Inputs	home, limit plus, limit minus, go, stop, pause, jog plus, jog minus, general purpose			
		Outputs	moving, fault, stall, velocity change, general purpose			
	Trip functions	Trip on input, trip on position, trip on time, trip capture, trip on relative position				
	Party mode addresses	62 (4)				
	Encoder functions	Find index				

(1) Actual power supply current will depend on voltage and load.  
 (2) When input voltage is removed, maintains power only to control and feedback circuits.  
 (3) Ethernet only available with MDrive23Hybrid systems.  
 (4) Only with RS-422/485 systems.

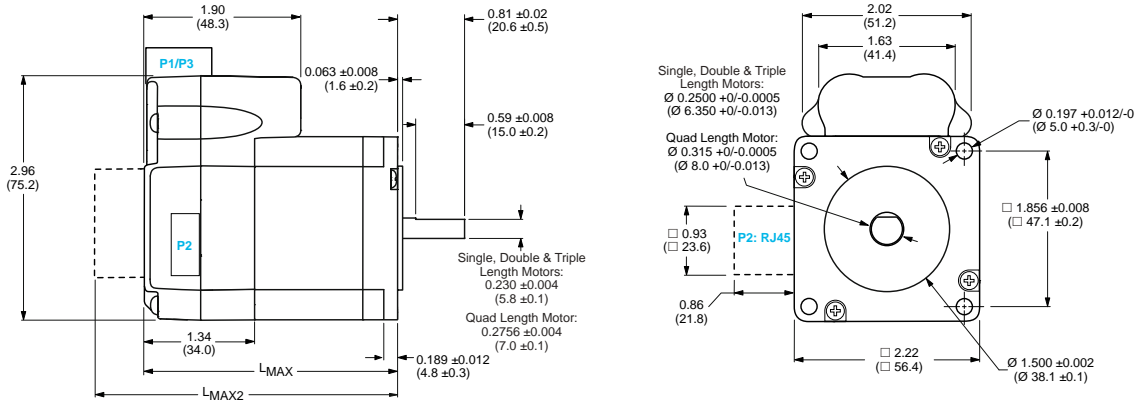
**Programming**

RS-422/485 MDrive Hybrid systems  
 Fully programmable. Users can quickly communicate and program via a PC using IMS Terminal, an integrated ASCII terminal emulator and program editor available for download at [www.imshome.com](http://www.imshome.com).

Ethernet MDrive Hybrid systems  
 These products support two protocols in a single package:  
 MCode/TCP — These fully programmable systems utilize Schneider Electric Motion USA's proprietary MCode programming language, developed for MDrive Motion Control products, which has been adapted to utilize TCP/IP message formatting.  
 MODBUS/TCP — A standard open industrial protocol supported by a variety of machine components such as programmable controllers, drives and controls, I/O modules and switches.

 See User Manual for complete details: [www.imshome.com/manuals.html](http://www.imshome.com/manuals.html)

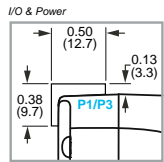
**Mechanical specifications, dimensions in inches (mm)**



Motor stack length	Lmax (1)	Lmax2 (2)
Single	2.65 (67.31)	3.36 (85.34)
Double	3.02 (76.71)	3.73 (94.74)
Triple	3.88 (98.55)	4.59 (116.59)
Quad	5.28 (134.15)	5.99 (152.19)

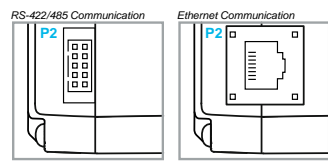
(1) Single shaft.  
(2) Control knob.

**P1/P3 connectors**



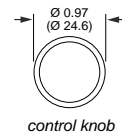
14- & 2-pin locking wire crimp connectors

**P2 connectors**

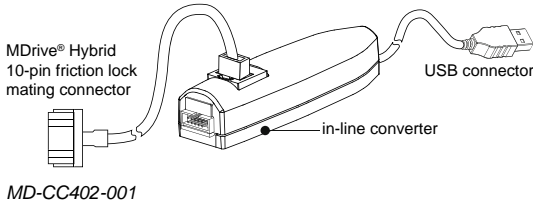


10-pin friction lock wire crimp connector  
RJ45 connector for Ethernet only

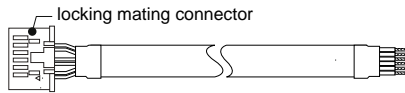
**Lmax2 option**



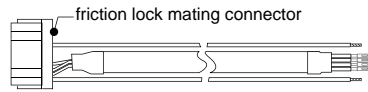
control knob



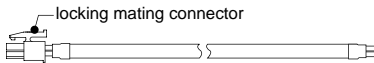
MD-CC402-001



PD14-2334-FL3



PD10-1434-FL3



PD02-2300-FL3

## Installation accessories

Description	Length feet (m)	Part number
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### QuickStart Kit

For rapid design verification, all-inclusive QuickStart Kits include connectivity, instructions and CD for MDrive Hybrid initial functional setup and system testing.

- For all MDrive23 Motion Control systems — add "K" to part number (1)

### Communication converter

Electrically isolated, in-line converter pre-wired with mating connector to conveniently set/program communication parameters for a single MDrive Hybrid via a PC's USB port.

- Mates to 10-pin friction lock wire crimp connector 12.0 (3.6) **MD-CC402-001**

### Prototype development cable

Speed test/development with pre-wired mating connector with other cable end open.

- Mates to 14-pin locking wire crimp connector for I/O 10.0 (3.0) **PD14-2334-FL3**
- Mates to 10-pin friction lock wire crimp connector for communication 10.0 (3.0) **PD10-1434-FL3**
- Mates to 2-pin locking wire crimp connector for power 10.0 (3.0) **PD02-2300-FL3**

### Mating connector kit

Connectors for assembly of cables, cable material not supplied. Sold in lots of 5. Manufacturer's crimp tool recommended for crimp connectors.

- 14-pin locking wire crimp connector for I/O — **CK-09**
- 10-pin friction lock wire crimp connector for communication — **CK-02**
- 2-pin locking wire crimp connector for power — **CK-04**

### Drive protection module

Limits surge current and voltage to a safe level when DC input power is switched on-and-off to an MDrive Hybrid.

- For all MDrive23 Motion Control systems — **DPM75**

(1) See page 28.

# MDrive® 23 Hybrid

Motion Control  
fully programmable

MDrive® 23 Hybrid



- P1: I/O**  
C = 14-pin locking wire crimp connector
- P3: Power**  
2-pin locking wire crimp connector
- P2: Communication**  
L = RS-422/485 with 10-pin friction lock wire crimp connector  
R = Ethernet with RJ45 locking connector

## Motion Control Part numbers

<b>Example:</b>	<b>K</b>	<b>M</b>	<b>A</b>	<b>I</b>	<b>3</b>	<b>C</b>	<b>R</b>	<b>L</b>	<b>2</b>	<b>3</b>	<b>A</b>	<b>6</b>	<b>-EJM</b>	<b>-N</b>
<b>QuickStart Kit</b> K = kit option, or leave blank if not wanted	<b>K</b>	<b>M</b>	<b>A</b>	<b>I</b>	<b>3</b>	<b>C</b>	<b>R</b>	<b>L</b>	<b>2</b>	<b>3</b>	<b>A</b>	<b>6</b>	<b>-EJM</b>	<b>-N</b>
<b>MDrive Hybrid version</b> MAI = Motion Control	<b>K</b>	<b>M</b>	<b>A</b>	<b>I</b>	<b>3</b>	<b>C</b>	<b>R</b>	<b>L</b>	<b>2</b>	<b>3</b>	<b>A</b>	<b>6</b>	<b>-EJM</b>	<b>-N</b>
<b>Type</b> 3 = HMT	<b>K</b>	<b>M</b>	<b>A</b>	<b>I</b>	<b>3</b>	<b>C</b>	<b>R</b>	<b>L</b>	<b>2</b>	<b>3</b>	<b>A</b>	<b>6</b>	<b>-EJM</b>	<b>-N</b>
<b>P1 connector</b> C = wire crimp	<b>K</b>	<b>M</b>	<b>A</b>	<b>I</b>	<b>3</b>	<b>C</b>	<b>R</b>	<b>L</b>	<b>2</b>	<b>3</b>	<b>A</b>	<b>6</b>	<b>-EJM</b>	<b>-N</b>
<b>Communication</b> R = RS-422/485 E = Ethernet	<b>K</b>	<b>M</b>	<b>A</b>	<b>I</b>	<b>3</b>	<b>C</b>	<b>R</b>	<b>L</b>	<b>2</b>	<b>3</b>	<b>A</b>	<b>6</b>	<b>-EJM</b>	<b>-N</b>
<b>P2 connector</b> L = wire crimp R = RJ45 (1)	<b>K</b>	<b>M</b>	<b>A</b>	<b>I</b>	<b>3</b>	<b>C</b>	<b>R</b>	<b>L</b>	<b>2</b>	<b>3</b>	<b>A</b>	<b>6</b>	<b>-EJM</b>	<b>-N</b>
<b>Motor size</b> 23 = NEMA 23 (2.3" / 57 mm)	<b>K</b>	<b>M</b>	<b>A</b>	<b>I</b>	<b>3</b>	<b>C</b>	<b>R</b>	<b>L</b>	<b>2</b>	<b>3</b>	<b>A</b>	<b>6</b>	<b>-EJM</b>	<b>-N</b>
<b>Motor length</b> A = single stack B = double stack C = triple stack D = quad stack	<b>K</b>	<b>M</b>	<b>A</b>	<b>I</b>	<b>3</b>	<b>C</b>	<b>R</b>	<b>L</b>	<b>2</b>	<b>3</b>	<b>A</b>	<b>6</b>	<b>-EJM</b>	<b>-N</b>
<b>Drive voltage</b> 6 = +12 to +60 VDC	<b>K</b>	<b>M</b>	<b>A</b>	<b>I</b>	<b>3</b>	<b>C</b>	<b>R</b>	<b>L</b>	<b>2</b>	<b>3</b>	<b>A</b>	<b>6</b>	<b>-EJM</b>	<b>-N</b>
<b>Encoder, differential</b> -EJM = 1000-line internal encoder	<b>K</b>	<b>M</b>	<b>A</b>	<b>I</b>	<b>3</b>	<b>C</b>	<b>R</b>	<b>L</b>	<b>2</b>	<b>3</b>	<b>A</b>	<b>6</b>	<b>-EJM</b>	<b>-N</b>
<b>Option</b> Leave blank if not wanted														<b>-N</b>

-N = rear control knob for manual positioning

(1) Only available with systems with Ethernet protocol.



Easy MDrive part numbers via an interactive tool at:  
[www.imshome.com/MDrivePlus.html](http://www.imshome.com/MDrivePlus.html)

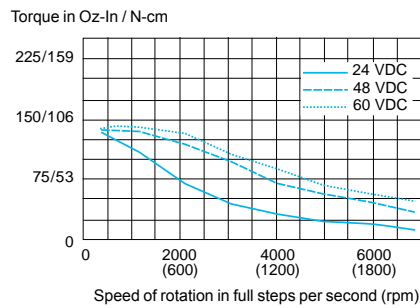
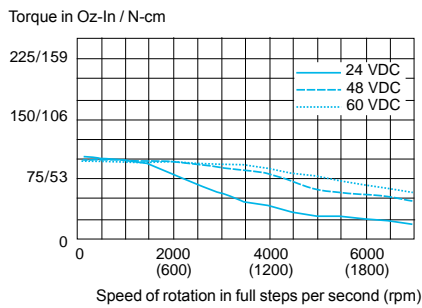
### Motor specifications MDrive 23 Hybrid

		Holding torque	Detent torque	Rotor inertia	Weight (motor + driver)
Motor stack length	Single	90.0 oz-in / 64.0 N-cm	3.9 oz-in / 2.7 N-cm	0.0025 oz-in-sec <sup>2</sup> / 0.18 kg-cm <sup>2</sup>	21.6 oz / 612.3 g
	Double	144.0 oz-in / 102.0 N-cm	5.6 oz-in / 3.92 N-cm	0.0037 oz-in-sec <sup>2</sup> / 0.26 kg-cm <sup>2</sup>	26.4 oz / 748.4 g
	Triple	239.0 oz-in / 169.0 N-cm	9.7 oz-in / 6.86 N-cm	0.0065 oz-in-sec <sup>2</sup> / 0.46 kg-cm <sup>2</sup>	39.2 oz / 1111.3 g
	Quad	283.0 oz-in / 200.0 N-cm	14.2 oz-in / 10.0 N-cm	0.0108 oz-in-sec <sup>2</sup> / 0.76 kg-cm <sup>2</sup>	61.6 oz / 1746.3 g

### Speed torque characteristics MDrive 23 Hybrid

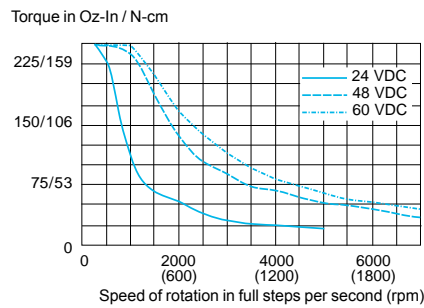
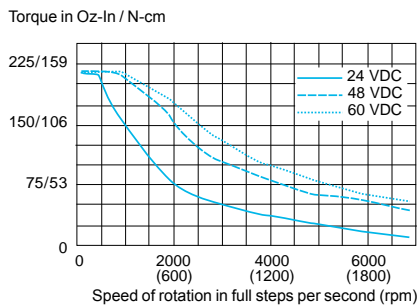
#### Single stack length

#### Double stack length



#### Triple stack length

#### Quad stack length



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e-mail: europe.sales@imshome.com

#### **TECHNICAL SUPPORT**

Tel. +00 (1) 860 295-6102 - Fax +00 (1) 860 295-6107  
e-mail: etech@imshome.com

#### **Schneider Electric Motion USA**

370 North Main Street, P.O. Box 457  
Marlborough, CT 06447 - U.S.A.  
Tel. +00 (1) 860 295-6102 - Fax +00 (1) 860 295-6107  
e-mail: info@imshome.com  
www.schneider-electric-motion.us